



## UNIVERSAL MULTIFRACTAL CHARACTERIZATION AND SIMULATION OF SPEECH

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In the 1970's it was found that, for low frequencies ( $< 10$  Hz), speech is scaling: it has no characteristic time scale. Now such scale invariance is associated with multiscaling statistics, and multifractal structures. Just as Gaussian noises frequently arise because they are generically produced by sums of many independent noise processes, scaling noises have an analogous universal behavior arising from nonlinear mixing of processes. We show that low frequency speech is consistent with these ideas, and use the measured parameters to produce stochastic speech simulations which are strikingly similar to real speech.

Although statistical methods such as spectrograms have frequently been applied to studying the properties of speech at audible frequencies, the study of low frequency components has been badly neglected. An important exception was Voss & Clarke [1975, 1978] (see also Pickover & Khorasani [1986]), who found that over the range  $\approx 10$  Hz to at least  $10^{-3}$  Hz, the spectrum had the scaling form  $f^{-\beta}$  with  $f$  the frequency, and  $\beta < 1$ . Scaling ideas now center on multifractals which involve an entire exponent function (rather than the single value  $\beta$ ). Furthermore, attractive (stable) universality classes exist for multifractal processes [Schertzer & Lovejoy, 1987, 1989, 1991]. For the same reason that — irrespective of the detailed generating mechanism — Gaussians occur in a wide variety of noise processes, in scaling noises, special types of (universal) multifractals naturally occur. When present, Gaussian distributions greatly simplify statistical analysis since they require only two basic parameters (the mean and variance) to specify the entire probability law. Universal multifractals play the same role in

scaling processes; with three parameters the entire (infinite hierarchy) of scaling exponents is specified. Indeed, universal multifractals have been empirically found in many scaling systems; turbulent velocity and temperature fields [Schertzer *et al.*, 1991; Schmitt *et al.*, 1992], cloud radiances [Gabriel *et al.*, 1988; Lovejoy & Schertzer, 1990; Tessier *et al.*, 1992], landscape topography [Lavallée *et al.*, 1992], ocean surfaces [Lavallée *et al.*, 1991a] and hadron jets [Brax & Peschansky, 1991; Ratti *et al.*, 1991].

To test these ideas on speech, recordings 890 seconds long were made using a standard eight-bit digitizer at 5.5 kHz. Seventeen samples of speech were studied including dictation and song, conversation, and subjects of both sexes, different ages, and speaking the French and English languages. Because of the physiology and anatomy of the phonatory apparatus, speech essentially consists of high frequency wave packets varying at much lower frequencies corresponding to phonemes, syllables, sentences and paragraphs. The low frequencies are

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essentially voluntary, involving significant muscular contraction and energy expenditure, whereas the high frequencies are primarily caused by small variations of the oscillations of the vocal chords and effects of minute valve action. At low frequencies, the only significant physiologically constrained time scale is at about 0.1 Hz associated with respiration. The cerebellum plays a critical role in the motor control of the low frequencies whereas the motor cortex does so for higher frequencies. The two regimes are therefore very different: using spectral analysis, we found that the transition (spectral minimum) occurs at about 10 Hz which separates the high frequency spectral bump (falling off quickly above 1 kHz) from the low frequency power law form discussed below. We concentrated on the low frequency part because it was apparently the simplest to analyze and model while having a greater neuropsychological significance due to its dependence upon higher order nonautomatic processing.

To isolate the low frequencies, we digitally low-pass filtered and resampled the signal at 9.8 Hz [Fig. 1(a)]. Visually, the signal is plausibly multifractal: it has structures at all scales as well as some very large values (the extreme singularities); for comparison, Fig. 1(b) shows a universal multifractal simulation. If the low frequency signal ( $A$ ) is the outcome of a scale invariant speech process, the statistical properties of the fluctuations ( $\Delta A$ ) over various time intervals ( $\Delta t$ ) will be related to each other by power laws of the scale ratios. Consider the fluctuations ( $\Delta A_\lambda$ ) at scale ratio  $\lambda$  obtained by degrading the original signal to resolution  $\Delta t = \tau/\lambda$  (i.e. its resolution is  $\lambda$  times smaller than that of the entire signal, duration  $\tau$ ). Its average value will depend on the resolution. It is therefore convenient to introduce a resolution independent multifractal speech process ( $\varphi_\lambda$ ) with the property  $\langle \varphi_\lambda \rangle = \text{constant}$  (" $\langle \rangle$ " indicates statistical averaging):

$$\Delta A_\lambda \approx \varphi_\lambda \lambda^{-H}, \quad (1)$$

where  $H$  quantifies the resolution dependence of the mean:  $\langle |\Delta A_\lambda| \rangle = \lambda^{-H}$ . The scaling  $\lambda^{-H}$  is equivalent to a "fractional integration" of order  $H$ , (a power law filter by  $f^{-H}$ ). Introducing  $K_A(q)$ ,  $K(q)$  to characterize the scaling of the  $q$ th statistical moment of  $A$ ,  $\varphi$  respectively, we obtain

$$\langle |\Delta A_\lambda|^q \rangle = \lambda^{K_A(q)} = \langle \varphi_\lambda^q \rangle \lambda^{-qH} = \lambda^{K(q)-qH}. \quad (2)$$

Resolution independence of  $\langle \varphi_\lambda \rangle$  implies that  $K(1) = 0$ , hence  $K_A(1) = -H$ . The spectral expo-

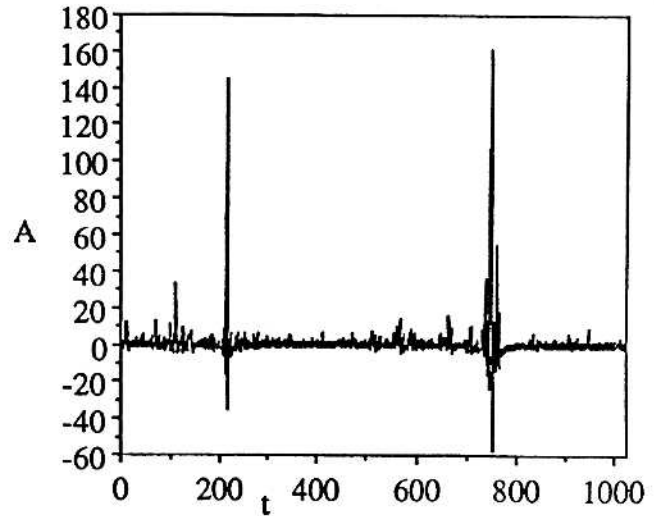


Fig. 1. (a)  $A \approx 100$  seconds long section of "As You Like It" filtered and resampled at 9.8 Hz. Note the extreme intermittency and asymmetry.

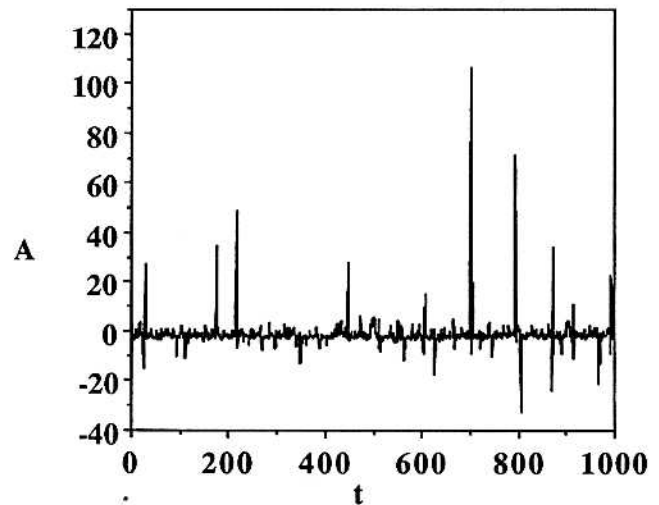


Fig. 1. (b) A stochastic universal multifractal simulation with  $H = -0.37$ ,  $C_1 = 0.1$ ,  $\alpha = 2$ , produced as described in Wilson *et al.* [1991]; the variability is plausibly of the same type as Fig. 1(a), changing the random seed in the Monte Carlo simulation produces a different mock speech record.

nent  $\beta$  mentioned above is given by  $\beta = 1 - K_A(2)$  (the energy spectrum is a second-order statistic). "Mono" scaling behaviour occurs if  $\varphi_\lambda$  has no resolution dependence,  $\langle \varphi_\lambda^q \rangle = \text{constant}$  for all  $q$  (not just  $q = 1$ ),  $K(q) = 0$  and  $K_A(q) = -qH$ ,  $\beta = 1 + 2H$ ; otherwise  $\varphi_\lambda$  is multiscaling and  $K(q)$  is convex. If we consider a multiscaling time series, then regions that exceed an amplitude threshold will have fractal dimensions that decrease with increasing threshold; intense parts of the signal will be distributed more sparsely in time than weaker

ones. In contrast, a monoscaling signal will have dimensions which are independent of the threshold. Figure 2 shows that the scaling (Eq. 2) is accurately followed over the entire range of available scales (with a slight bump possibly associated with the respiratory frequency at  $\lambda \approx 200$ ), and Fig. 3 shows the  $K(q)$  obtained by regression on Fig. 2, after removing the term  $qH$  ( $H \approx -0.37 \pm 0.01$ ). It is clearly convex; low frequency speech is therefore multiscaling.

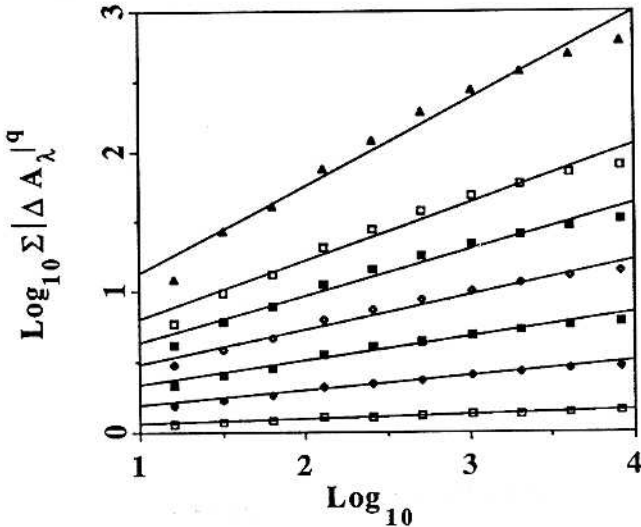


Fig. 2. The (log) sum over all disjoint intervals of the  $q$ th moment of the absolute speech fluctuation ( $\Sigma |\Delta A_\lambda|^q \approx \lambda^{K_A(q)-(q-1)}$ ) as a function of the (log) scale ratio  $\lambda$ . From top to bottom  $q = 1.5, 1.1, 0.9, 0.7, 0.5, 0.3, 0.1$ .  $K_A(q)$  is determined from the slope. Note that the multiple scaling is well followed over the entire range corresponding to  $\approx 10$  Hz to  $10^{-3}$  Hz.

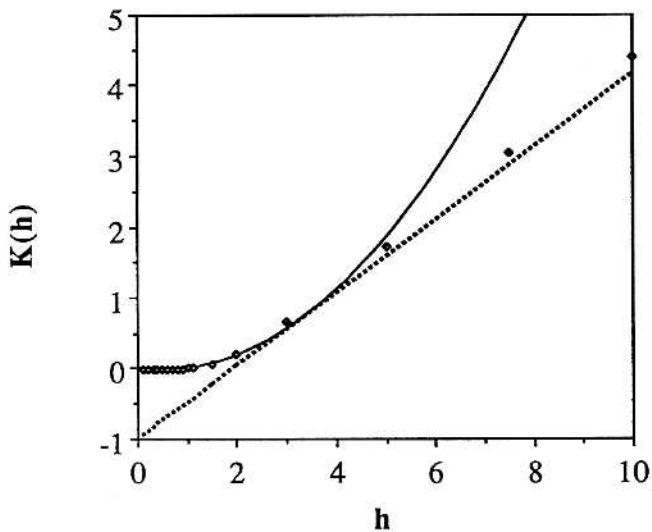


Fig. 3. The empirical  $K(q)$  function obtained by subtracting  $qK_A(1)$  from the slopes of Fig. 2, with the optimum piecewise quadratic/linear fit (Eq. 4) with  $C_1 = 0.09$ .

If  $\varphi$  is the result of nonlinear “mixing” (interaction) of many different processes [Schertzer & Lovejoy, 1987, 1989; Fan, 1989], most of the details of the process will be irrelevant and we may expect it to have the following universal form:

$$K(q) = \frac{C_1}{\alpha - 1} (q^\alpha - q), \quad (3)$$

where  $C_1$  is the codimension of the mean of  $\varphi_\lambda$  (in the one-dimensional time series here,  $0 \leq C_1 \leq 1$  and the corresponding fractal dimension of the mean is  $1 - C_1$ ). It represents the best monofractal approximation to the mean.  $\alpha$  is the Levy exponent and characterizes the degree of multifractality.

It is fairly straightforward to estimate  $C_1$ ; this can be done from,  $K'(1) = C_1$  (yielding  $C_1 \approx 0.09 \pm 0.01$ ).  $\alpha$  is more difficult to estimate since it determines the concavity, and hence deviation from monofractality;  $\alpha = 2$  is the maximum,  $\alpha = 0$ , the monofractal (minimum). A new method for estimating  $\alpha$ , called the “Double Trace Moment” technique [Schertzer *et al.*, 1991; Lavallée, 1991], indicates that  $\alpha = 1.95 \pm 0.1$ , i.e. near its maximum: indeed, a quadratic ( $\alpha = 2$ ) fit (Fig. 3) for the range  $0 < q < 3$ , yields an RMS error of only  $\pm 0.02$ . The reason for this range restriction is that, above a critical value  $q_c$ , the empirical moments are no longer accurate estimates of the true (ensemble averaged) moments: we will expect a discontinuity in the slope and a linear behavior for the measured  $K(q)$  for  $q < q_c$  (as observed in Fig. 3 for  $q > 3$ ).  $q_c$  can arise through two quite distinct causes (which mimic multifractal “phase transitions” [Schertzer *et al.*, 1992]):

- (a) there is undersampling [Lavallée, 1991; Lavallée *et al.*, 1991]: any finite sample has a maximum order of singularity, hence all moments  $q > q_s$  will be dominated by this value; this yields a second order phase transition;
- (b) there is divergence of moments; for  $q > q_D$ , the theoretical  $K(q)$  is infinite, and we detect a “spurious” scaling again characterized by a linear  $K(q)$  for  $q > q_D$ ; this yields a first order phase transition.

For a single sample in one dimension ( $D = 1$ ), we obtain ( $\alpha = 2$ ):  $q_s = C_1^{-1/2}$ ,  $q_1 = C_1^{-1}$  (hence

$q_s < q_1$ ). The overall empirical moments will follow:

$$K(q) = \begin{cases} C_1(q^2 - q), & q < C_1^{-1/2}, \\ q(2C_1^{1/2} - C_1) - 1, & q > C_1^{-1/2}. \end{cases} \quad (4)$$

Using  $C_1 = 0.09$ , we find  $q_c = q_s \approx 3.30$ : Figure 3 shows that an excellent fit is obtained over the entire range  $0 < q < 10$  (the maximum distance between the theoretical and empirical curves is 0.06).

For the other series we investigated, results were generally similar;  $\alpha$  near 2,  $C_1$  in the range 0.09 to 0.18 (a selection of opera singing yielding the largest). Just as many different nonscaling processes can give rise to Gaussian noises, so many different scaling mechanisms for speech can give rise to universal multifractals with the same basic parameters. Traditional analysis methods have concentrated on the high frequency part of the spectrum using spectrograms and other methods sensitive to small differences in signal statistics: In contrast the universality parameters here are extremely insensitive to these differences. For this very reason, they quantify a very fundamental aspect of the speech process and help us rule out models of speech which break the scaling by introducing specific processes at well-defined time scales. Knowledge that low frequency speech fits into these broad universal categories will be important in improving our understanding of the high frequencies too. It also suggests other analyses — for example, the scaling of the distribution of tagged phenomena, syllables etc. that could be performed in the future. Finally, to demonstrate the usefulness of our characterization, we used continuous cascade processes [Schertzer & Lovejoy, 1987, 1989; Fan, 1989; Wilson et al., 1991] calibrated with the measured parameters, to make simulated low frequency speech signals [see Fig. 2(b)]. These could provide the basis for full simulations by providing a signal to modulate the higher frequencies.

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